

Announcements

1. First quiz live now, due Friday

- Administered through Canvas
- One question, multiple choice
- 20 minutes
- Covers basic logic (Tuesday's lecture, this week's tutorial, posted notes)
- **Don't start until you're ready to take the quiz.**

2. Programming Assignment 1 released next week

- Due 13 November

3. Attendance Code: 825332

Meeting Goals

- Finish discussion of mathematical induction
- Analyze algorithm correctness with loop invariants
- Formalize the RAM model of computation
- Introduce asymptotic notation

Mathematical Induction

Mathematical Induction

statement T or F
for each nat. #

The Principle of Mathematical Induction

Let P be a predicate over the natural numbers $\mathbf{N} = \{0, 1, 2, \dots\}$. Suppose P satisfies

- **Base case:** $P(0)$ is true.
- **Inductive step:** For every $i \in \mathbf{N}$, $P(i) \implies P(i+1)$.

Then for every $n \in \mathbf{N}$, $P(n)$ is true. In strictly symbolic notation:

$$(P(0)) \wedge (\forall i [P(i) \implies P(i+1)]) \implies \forall n P(n).$$

Loop Invariants

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Given an algorithm A containing a loop, a **loop invariant** is a predicate P on the iterations of the loop such that for each iteration i , $P(i)$ is satisfied at the end of the i -th iteration of the loop.

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An Uninteresting Example

Consider the following procedure

```
1: procedure COUNT( $n$ )  
2:    $t \leftarrow 0$   
3:   for  $i = 1, \dots, n$  do  
4:      $t \leftarrow t + 1$   
5:   end for  
6:   return  $t$   
7: end procedure
```

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After iteration i , t stores the value i .

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```

Base case

by ind. hyp
 $t = i$ in $(i+1)$
iteration

Loop Invariant

After iteration i , t stores the value i .

Induct on i

- Base case: t initialized to 0. (Line 2)
- Inductive step:
 - Suppose after iteration i , t stores the value i (inductive hypothesis)
 - Then in iteration $i+1$ after line 4, t stores the value $i+1$.

A More Interesting Example

1: **procedure** MININDEX((a, i, k)) \triangleright
Find the index of the minimum value stored in array a between indices i and k .

2: $m \leftarrow i$

3: **for** $j = i, i + 1, \dots, k$ **do**

4: **if** $a[j] > a[m]$ **then**

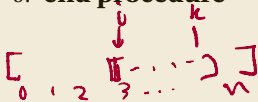
5: $m \leftarrow j$

6: **end if**

7: **end for**

8: **return** m

9: **end procedure**



PollEverywhere Question

What loop invariant does the loop in MININDEX satisfy that will help us analyze its behavior?



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A More Interesting Example



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Loop Invariant

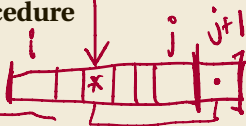
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```

compare



Loop Invariant

After iteration j , m stores the index of the minimum value of a between indices i and j .

Proof.

Induct on j

- Base case: $j = i$.
- Inductive step:
 $j \Rightarrow j + 1$



Further Application

Consider the following algorithm that uses `MININDEX` as a subroutine:

```
1: procedure SELECTIONSORT( $a, n$ )           ▷ Sort the array  $a$  of size  $n$ 
2:   for  $i = 1, 2, \dots, n$  do
3:      $j \leftarrow \text{MININDEX}(a, i, n)$ 
4:     SWAP( $a, i, j$ )
5:   end for
6: end procedure
```

Exercise (Tutorials)

Show that `SELECTIONSORT` correctly sorts any array a of length n .
Specifically:

- Find a suitable loop invariant satisfied by `SELECTIONSORT`
- Prove your loop invariant holds (by induction)
- Argue that your loop invariant implies the final array is sorted

Induction and Recursion

Induction is essential in reasoning about *recursively defined* methods.

A Recursive Method

```
1: procedure MYSTERY(n)
2:   if n = 1 then
3:     return 1
4:   end if
5:   return  $2n - 1 + \text{MYSTERY}(n - 1)$ 
6: end procedure
```

$$\begin{aligned} & \text{Mystery}(2) \\ & 2^{2-1} + \text{Mystery}(1) \\ \Rightarrow & 2 \cdot 2^{-1} + 1 = 4 \end{aligned}$$

PollEverywhereQuestion

What is the output of MYSTERY(5)?



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Analysis of a Mystery

```
1: procedure MYSTERY( $n$ )
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For all n , MYSTERY(n) returns the value n^2 .

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Claim

For all n , MYSTERY(n) returns the value n^2 .

Proof.

Induction on n . Base Case: $n = 1$. *line 3*

Inductive step: Suppose MYSTERY(n) = n^2 . Then

$$\underline{\text{MYSTERY}(n+1)} = 2n + 1$$

$$+ \text{MYSTERY}(n)$$

$$= 2n + 1 + \boxed{n^2}$$

$$= (n+1)^2.$$

inductive hypothesis

Modelling Computation

What is an Algorithm?

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1. is mechanically executable

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compute
 $x+y$ for
any x and y

compute
 $3+7$

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input → processing → output

Example

The SELECTIONSORT algorithm

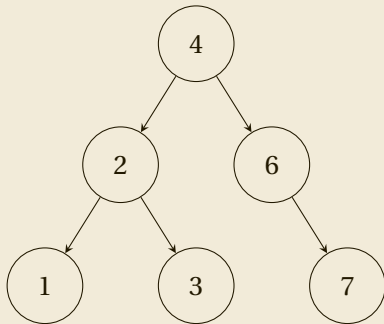
- sorts *any* array of size n
- elementary operations/logic

What is a Data Structure?

A **data structure** is

1. a rule for *encoding data* in computer memory, and
2. algorithms for accessing and manipulating the data according to the specified encoding.
 - See next week for much more detail!

Typical example: binary search trees



What Makes an Algorithm “Good?”

Overarching Goal: find the “best” algorithm and data structures for a task

1. **Correctness:** the algorithm performs the **specified task...**
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Algorithm analysis gives us a way to

- compare different algorithms
- predict their performance (efficiency) in applications

Limitations of Empirical Analysis

Question. Why not just implement your algorithm and test it on a real computer with real data?

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Our Focus is **formal analysis** of algorithms on an abstract computer

- *prove* results for our computational model
- results apply to any computer that satisfy our assumptions

Note. Neither formal nor empirical analysis is *better*—both are important to computer science!

- this module just focuses on formal analysis

Data Models

To perform formal algorithm analysis, we must specify

1. the computational model
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Types of performance:

- **worst-case performance**

Over all possible inputs, what is the *worst* cost of our algorithm's execution?

- **best-case performance**

Over all possible inputs, what is the *best* cost of our algorithm's execution?

- **average-case performance**

What is the *average* or *expected* cost for a of a *random* input

Typically, we analyze performance as a function of **input size**, n

\implies measure performance as a function of n : how does performance scale with input size

Computational Models

A **computational model** defines

1. *syntax*: what operations can be performed
2. *semantics*: what are the effects of those operations
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These features determine what problems can be solved and with what efficiency

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Successful & general computational models defined in the 1930's



Credit: Princeton University

Alonzo Church
(Lambda Calculus)



Credit: Unknown

Alan Turing
(Turing Machines)

Random Access Machines

The RAM Model consists of:

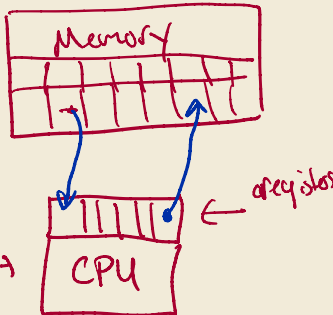
- Unlimited **memory**, access by address
 - stores program, input, intermediate data
 - each address stores fixed sized “word”
- Fixed number of **registers**
 - stores “working” data
- Elementary **instructions**
 - load & store: move data between registers/memory
 - arithmetic operations: bit-wise ops, addition/subtraction (fixed precision),...
 - conditional/unconditional jump
- **cost** = number of instructions executed



Credit: LANL

Jon von Neumann

RAM is a standard model for *sequential* computation, similar to assembly



Pseudocode

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Simplifying abstractions:

- Higher level abstract **pseudocode**:
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Pseudocode can (in principle) be implemented in RAM model, just as C++ can be compiled to assembly

divisor

```
procedure EUCLID( $a, b$ )  
  while  $b \neq 0$  do  
     $t \leftarrow b$   
     $b \leftarrow a \bmod b$   
     $a \leftarrow t$   
  end while  
  return  $a$   
end procedure
```

Greatest Common
~~denominator~~
of a b

(Important) Things We Ignore

System & Hardware Level Details

- Memory allocation
 - required to implement arrays, dynamic memory usage, etc
- Pointers
 - correspondence between variable names, values, and memory addresses
- Support for procedures/methods/functions
 - call stack, call frame, etc.

This are all fundamental problems in computer science, just not within the purview of COMP526

- See modules on operating systems, compilers, programming languages, etc.

Asymptotic Notation

Measuring (Time) Efficiency

Recall. We measure *(time) efficiency* in terms of number of elementary operations performed

- assume all operations are unit cost

We want a **robust** measure of efficiency that is *independent* of particular “real world” costs of operations

- focus on how the number of operations **scales** with input size

Measuring (Time) Efficiency

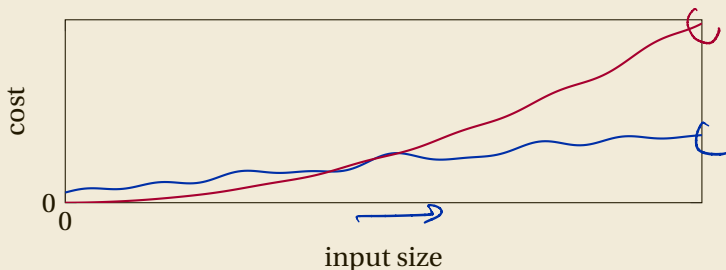
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This motivates the study of **asymptotic analysis**.



Big-O Notation

Goal of “Big- O ” or asymptotic notation: a way of describing the *growth* of functions that is:

- **coarse** enough to be simple enough to analyze
 - independent of hardware or implementation constants
- **precise** enough to be informative

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Definition

Suppose f and g are functions from \mathbf{N} to \mathbf{R}^+ . Then we say that $f = O(g)$ (read: f is *big O* of g) if there exist constants $N_0 \in \mathbf{N}$ and $C \in \mathbf{R}$ such that for all $n \in \mathbf{N}$

$$n \geq N_0 \implies f(n) \leq Cg(n).$$

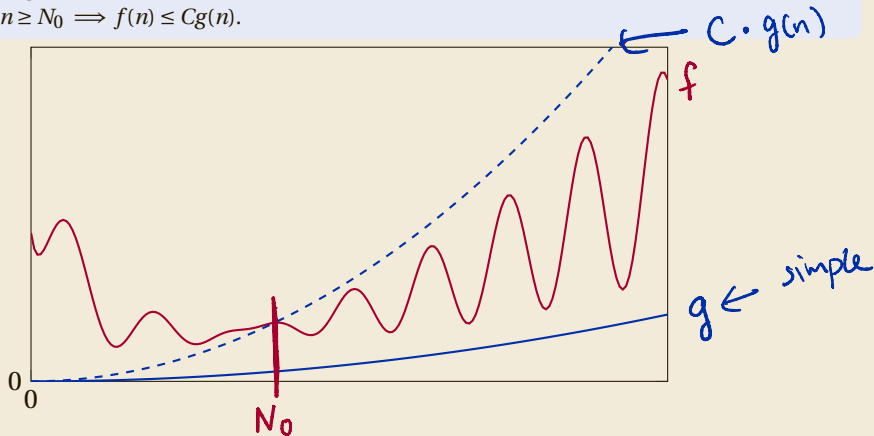
Equivalently, $f = O(g) \iff \limsup \frac{f(n)}{g(n)} < \infty$

natural #'s (input size)
cost

Big-O in Pictures

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Properties of O

Proposition

Suppose $f, f_1, f_2, g, g_1, g_2, h$ are functions and a is any constant. Then:

1. $(\forall n \underline{f(n) \leq a}) \implies \underline{f = O(1)}$ *f is bounded by a*
2. $(\forall n \underline{f(n) \leq g(n)}) \implies f = O(g)$
3. $\underline{f = O(g)} \implies a \cdot f = O(g)$
4. $f = O(g)$ and $g = O(h) \implies f = O(h)$ *transitive $a < b$
 $b < c \implies a < c$*
5. $f = O(h)$ and $g = O(h) \implies f + g = O(h)$
6. $f_1 = O(g_1)$ and $f_2 = O(g_2) \implies f_1 \cdot f_2 = O(g_1 \cdot g_2)$

Consequence:

- If $a \leq b$ then $n^a = O(n^b)$

Exercise. Show that if $a > b$, then $n^a \neq O(n^b)$.

Example with Functions

$\mathcal{O}(n^{100})$

Analyze the asymptotic growth of

$$f(n) = 17n^2 + 42n + 38\sqrt{n} + 972$$

$19n^3 +$

$\mathcal{O}(n^2)$

$\mathcal{O}(n)$

$\mathcal{O}(n^{1/2})$

$\mathcal{O}(1)$

n^0

$\mathcal{O}(n^2)$

$\mathcal{O}(n^2)$

1. $(\forall n f(n) \leq a) \Rightarrow f = \mathcal{O}(1)$

2. $(\forall n f(n) \leq g(n)) \Rightarrow f = \mathcal{O}(g)$

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5. $f = \mathcal{O}(h)$ and $g = \mathcal{O}(h) \Rightarrow f + g = \mathcal{O}(h)$

6. $f_1 = \mathcal{O}(g_1)$ and $f_2 = \mathcal{O}(g_2) \Rightarrow f_1 \cdot f_2 = \mathcal{O}(g_1 \cdot g_2)$

$2 \Rightarrow n^2 = \mathcal{O}(n^2)$

$3 \Rightarrow w/ a = 17$
 $17n^2 = \mathcal{O}(n^2)$

$\mathcal{O}(n^2)$

Example with Pseudocode

Example. Analyze the *worst-case* running time of the INSERTIONSORT procedure defined below.

- assume elementary operations have running time $O(1)$.

```
1: procedure INSERTIONSORT( $a[n]$ )
2:   for  $i = 2, 3, \dots, n$  do
3:      $j \leftarrow i$ 
4:     while  $j > 1$  and  $a[j-1] < a[j]$  do
5:       SWAP( $a, j-1, j$ )
6:        $j \leftarrow j-1$ 
7:     end while
8:   end for
9: end procedure
```

$a[n]$ ← size of array
array

$j \leftarrow i$ $O(1)$

while $j > 1$ and $a[j-1] < a[j]$ **do**

SWAP($a, j-1, j$) $O(1)$

$j \leftarrow j-1$ $O(1)$

end while

end for

end procedure

$\leq n$
 $\leq i$ iterations
 $O(i) = c \cdot i$
Inner loop time
 $= O(n)$

Analysis of outer loop
 $\leq n$ iterations

Overall running time is $O(n^2)$.

Best Case Running Time

```
1: procedure INSERTIONSORT( $a, n$ )
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Consider sorted a
 $a[1] \leq a[2] \leq a[3] \leq \dots$

Not satisfied
so $O(1)$ if sorted

PollEverywhere Question

What is the **best case** running time for INSERTIONSORT? What arrays incur this running time?



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Variations of O

- $f = \Theta(g)$ if $f = O(g)$ and $g = O(f)$
 - Example: $4n^2 + 3n + 7 = \Theta(n^2)$
- $f = \Omega(g)$ if $g = O(f)$
 - Example: $0.01n^2 - 7n = \Omega(n^2)$
- $f = o(g)$ if for every $\varepsilon > 0$, there exists N_0 such that $n \geq N_0 \implies \frac{f(n)}{g(n)} < \varepsilon$.
 - Equivalently: $f = o(g) \iff \lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0$
 - Example: $n^{1.999} = o(n^2)$
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Mnemonic for Variations

Big-O	(in)equality
ω	$>$
Ω	\geq
Θ	\approx
O	\leq
o	$<$

Interpretation

Suppose:

- two algorithms A and B for solving the same problem
- running time of A is f , running time of B is g
- $f = o(g)$

Consider running A on a **slow** machine M_1 and B on a **fast** machine M_2 .
Then: regardless of how much slower M_1 is than M_2 , for *sufficiently large* inputs, A will complete faster than B .

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The Moral. Efficient *algorithms* are better than faster hardware.

- little- o notation gives the “right” abstraction to formalize this relationship

Common Orders of Growth

Named orders of growth:

name	asymptotic growth
constant	$O(1)$
logarithmic	$O(\log n)$
polylogarithmic	$O(\log^c n)$
linear	$O(n)$
almost linear	$O(n \log^c n)$
quadratic	$O(n^2)$
polynomial	$O(n^c)$
exponential	$O(c^n)$

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name	asymptotic growth
constant	$O(1)$
logarithmic	$O(\log n)$
polylogarithmic	$O(\log^c n)$
linear	$O(n)$
almost linear	$O(n \log^c n)$
quadratic	$O(n^2)$
polynomial	$O(n^c)$
exponential	$O(c^n)$

Relationships

Between classes:

For all $a, b > 0$

- $a = o(\log^b n)$
- $\log^a n = o(n^b)$
- $n^a = o(b^n)$

Common Orders of Growth

Named orders of growth:

name	asymptotic growth
constant	$O(1)$
logarithmic	$O(\log n)$
polylogarithmic	$O(\log^c n)$
linear	$O(n)$
almost linear	$O(n \log^c n)$
quadratic	$O(n^2)$
polynomial	$O(n^c)$
exponential	$O(c^n)$

Relationships

Between classes:

For all $a, b > 0$

- $a = o(\log^b n)$
- $\log^a n = o(n^b)$
- $n^a = o(b^n)$

Within classes:

For all $a, b, a < b$

- $\log^a n = o(\log^b n)$
- $n^a = o(n^b)$
- $a^n = o(b^n)$

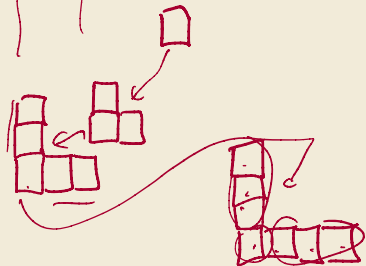
Next Time

- Abstract Data Types
- Fundamental Data Structures

Scratch Notes

$$M(5) = 2 \times 5 - 1 + M(4)$$

$$1 + 3 + 5 + 7 \dots + 2k - 1 = k^2$$



$$2 \times 4 - 1 + M(3)$$

$$2 \times 3 - 1 + M(2)$$

Scratch Notes
